

# Primer: conditional probabilities

Lecture 7.1

*by Marina Barsky*



# BOOLEAN-VALUED RANDOM VARIABLES

# Discrete Boolean **random** variables

A is a Boolean-valued random variable if A denotes an event, and there is some **degree of uncertainty** as to whether A occurs or not.

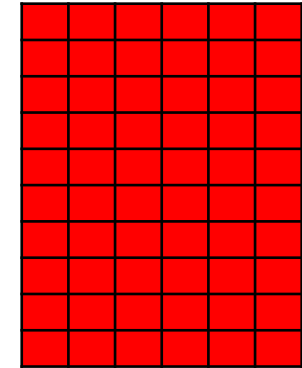
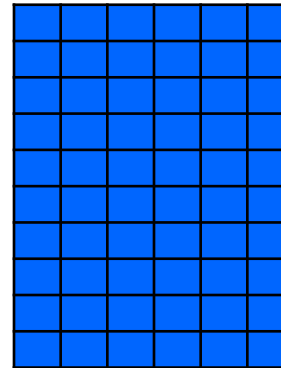
Examples:

- $P = \text{True}$ : The US president in 2023 will be male
- $P = \neg \text{True}$ : The US president will not be a male
- $H = \text{True}$ : You wake up tomorrow with a headache
- $H = \neg \text{True}$ : No headache

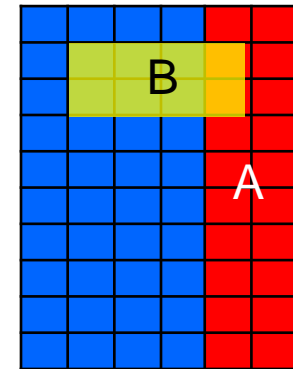


# Axioms

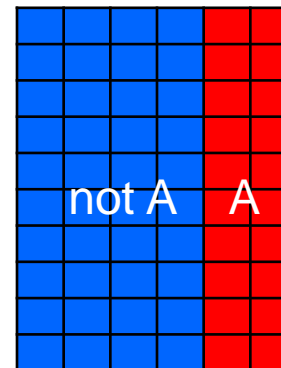
I.  $0 \leq P(A=a) \leq 1.0$



II.  $P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$



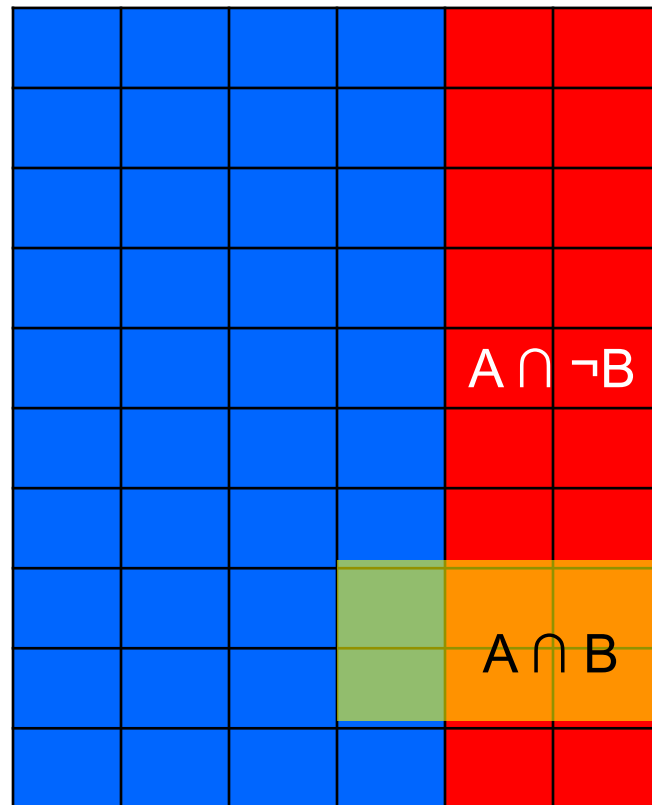
III.  $P(A) + P(\neg A) = 1.0$





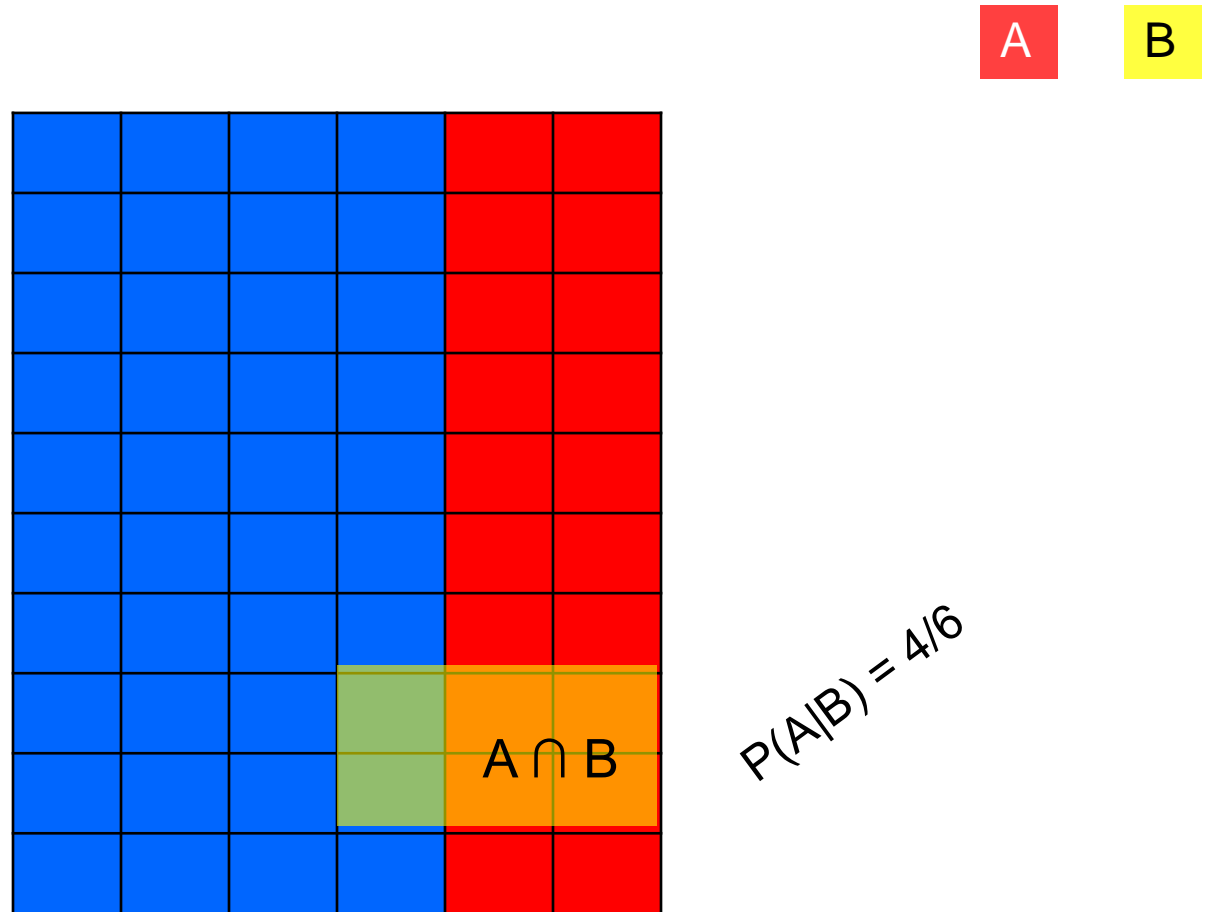
# Theorem 2

$$P(A) = P(A \cap B) + P(A \cap \neg B)$$



# Conditional probability: definition

- $P(A|B)$  = fraction of worlds in which A is true out of all the worlds where B is true

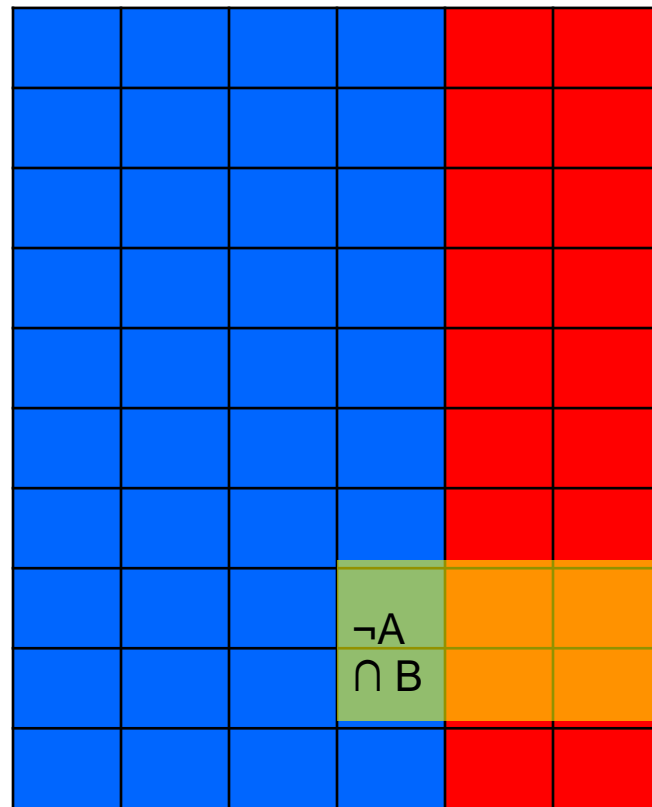


CP definition:  $P(A|B) = P(A \cap B) / P(B)$



# Conditional probability: definition

- $P(A|B)$  = fraction of worlds in which A is true out of all the worlds where B is true

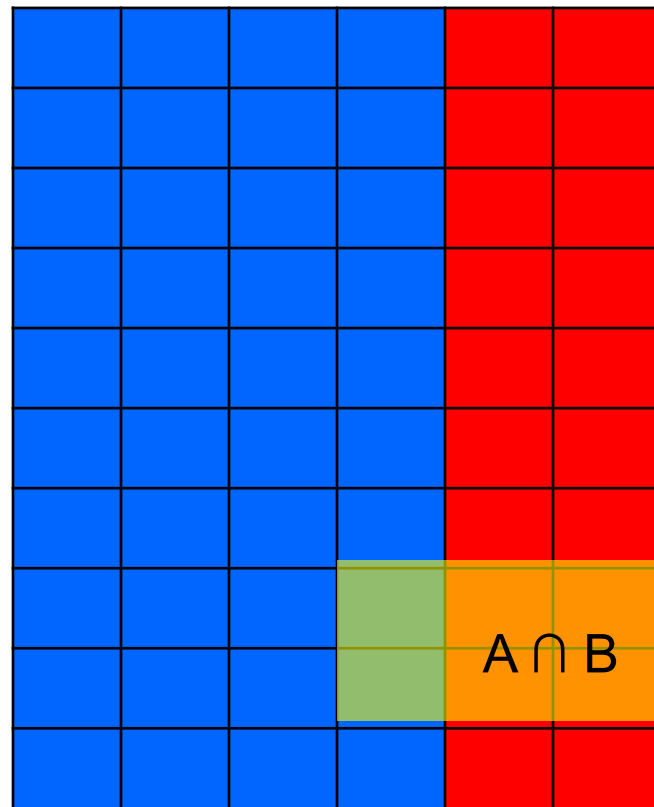


$$P(\neg A|B) = 2/6$$

$$P(\neg A|B) = P(\neg A \cap B) / P(B)$$

# Conditional probability: definition

- $P(B|A)$  = fraction of worlds in which B is true out of all the worlds where A is true



$P(B) = 6/60 = 0.1$  (unconditional)  
 $P(B|A) = 4/20 = 0.2$  (conditional)

$$P(B|A) = P(A \cap B) / P(A)$$

$$P(A \cap B) = 4/60$$

$$P(A) = 20/60$$

$$P(B|A) = 4/60 : 20/60 = 0.2$$

# Probabilistic independence

Two random variables A and B are called *mutually independent* if

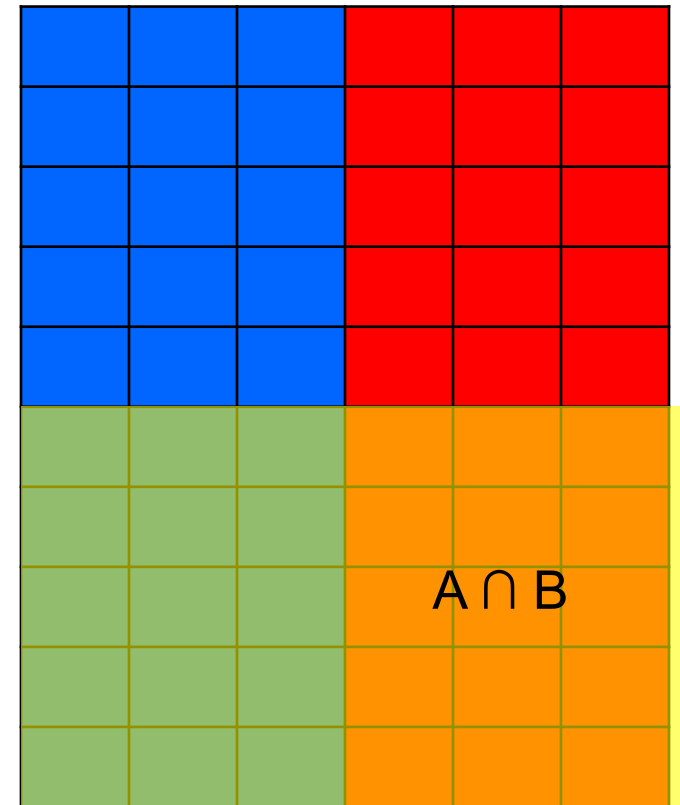
$$P(A | B) = P(A):$$

$$P(A | B) = P(A) \quad 15/30 = 30/60$$

$$P(\neg A | B) = P(\neg A) \quad 15/30 = 30/60$$

$$P(A | \neg B) = P(A) \quad 15/30 = 30/60$$

$$P(\neg A | \neg B) = P(\neg A) \quad 15/30 = 30/60$$



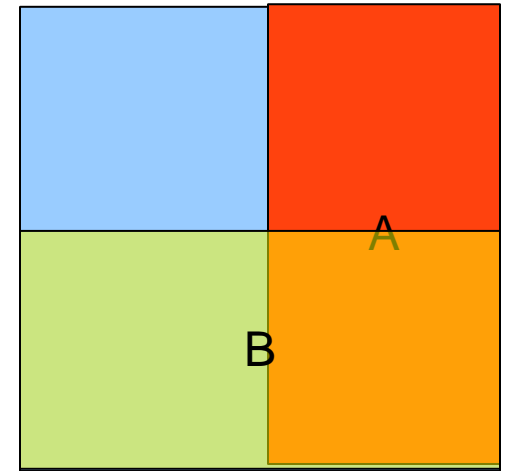
Knowing that B is true (or false) does not change the probability of A



# Independent and mutually exclusive events

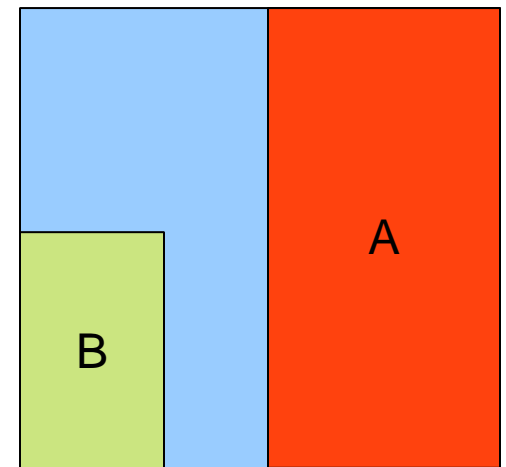
A is *independent* of B: knowing that B is true (or false) does not change the probability of A:

$$P(A|B) = P(A)$$



A and B are *mutually exclusive* – **not independent** variables: if A is true then B is false, if A is false then B is true with probability  $P(B|\neg A)$

$$P(A \cap B) = 0$$



# Probability of two independent events

From the definition of conditional probabilities:

$$P(A|B) = P(A \cap B) / P(B)$$

we can compute  $P(A \cap B)$  – that both events happened together:

$$P(A \cap B) = P(A|B)P(B)$$

If A and B are *independent* that becomes:

$$P(A \cap B) = P(A)P(B)$$



# Probabilistic inductive reasoning

- Critical thinking: always have good reasons for your beliefs
- Some reasons may be 100% true - some only probable
- Inductive reasoning with probabilities: you always have a chance of being wrong

<http://www.starwars.com/video/never-tell-me-the-odds>

*I believe that John will not be at the party*

In the absence of facts

John will **not** be at the party



What are the odds?



*I believe that John will not be at the party*

Invalid (illogical) reasoning

I do not like John



John will **not** be at the party

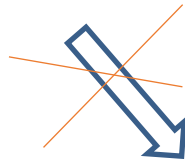


What are the odds?

*I believe that John will not be at the party*

Probabilistic reasoning: valid fact (evidence)

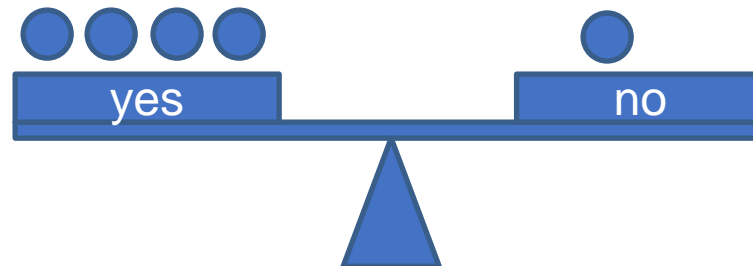
I do not like John



John is very shy



John will **not** be at the party



What are the odds given this fact?

*I believe that John will not be at the party*

More facts – update your beliefs

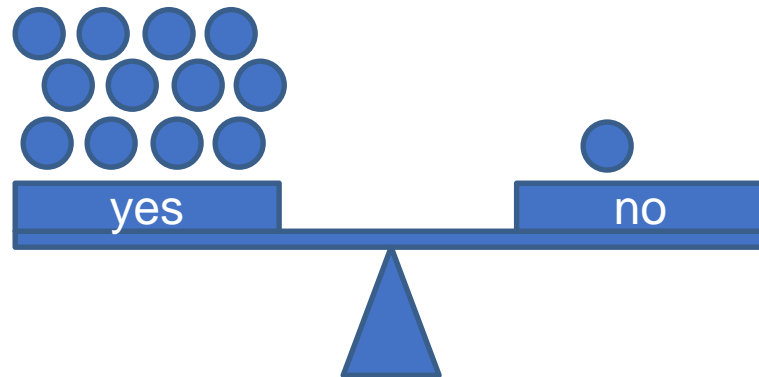
I do not like John

John is in Beijing

John is very shy



John will **not** be at the party



What are the odds?

# Bayesian beliefs

- How do we judge that something is true?
- Can mathematics help make judgments more accurate?
- Bayes: **our beliefs should be updated** as new evidence becomes available



*T. Bayes.*

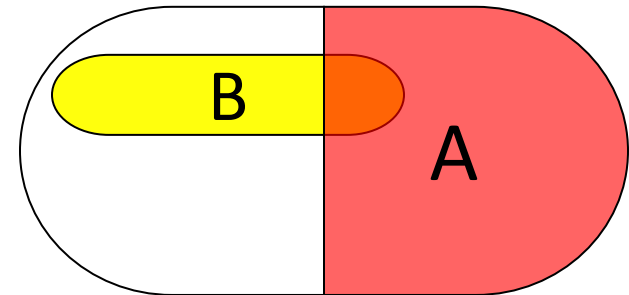
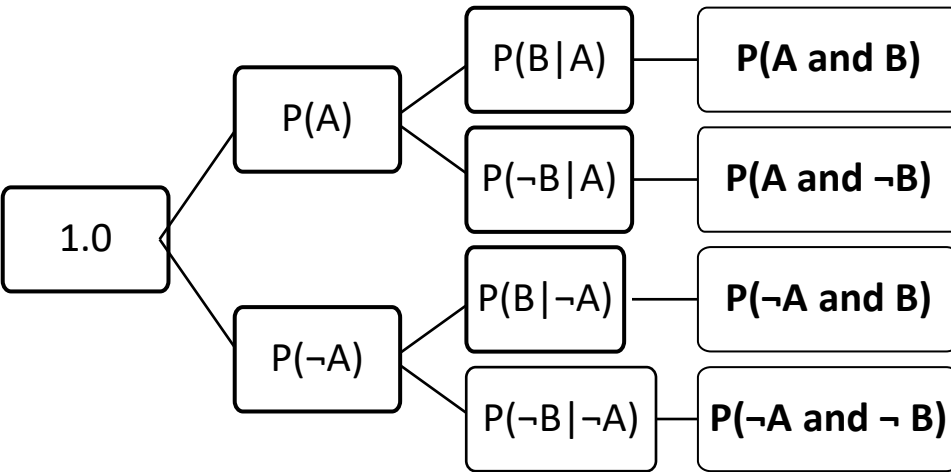
1701 - 1761

# Bayes' method for updating beliefs

- There are 2 mutually exclusive events: **A** and not A (**B**) which you believe occur with probabilities  $P(\mathbf{A})$  and  $P(\mathbf{B})$ . Estimation  $P(\mathbf{A}):P(\mathbf{B})$  represents *odds* of A vs. B.
- Collect evidence data **E**.
- Re-estimate  $P(\mathbf{A} | \mathbf{E}):P(\mathbf{B} | \mathbf{E})$  and update your beliefs.

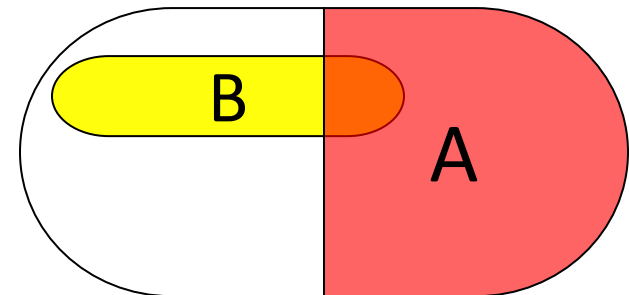
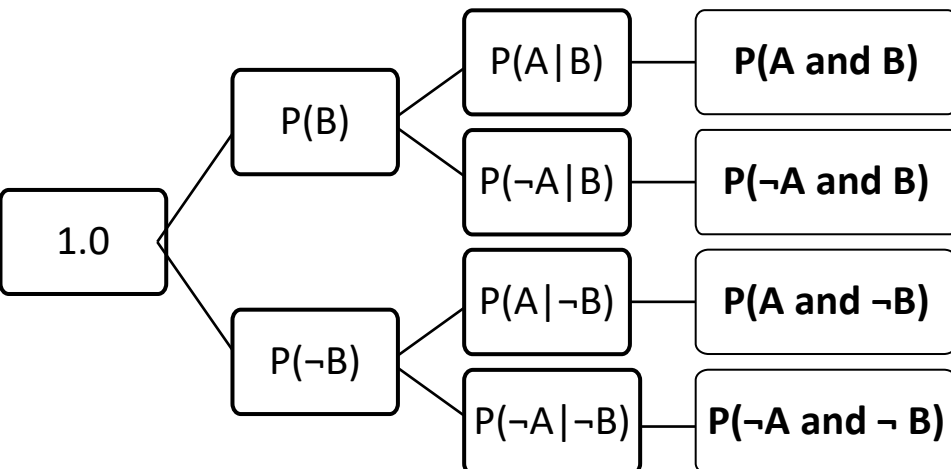
$$P(A) = 1/2, P(B) = 1/6$$

Two random events (not independent) happen at the same time –  $P(A \text{ and } B)$



Possible event combinations when we know the outcome of event A:

$$P(A)=1/2, P(B|A)=1/12 \text{ and } P(A \text{ and } B)=1/2*1/12 = 1/24$$

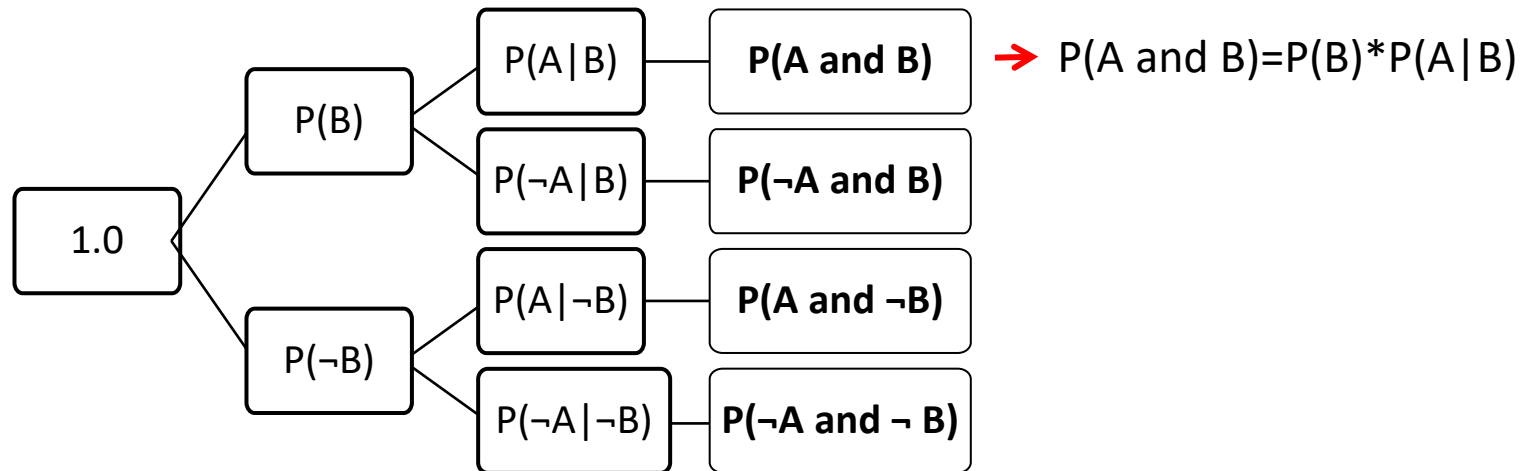
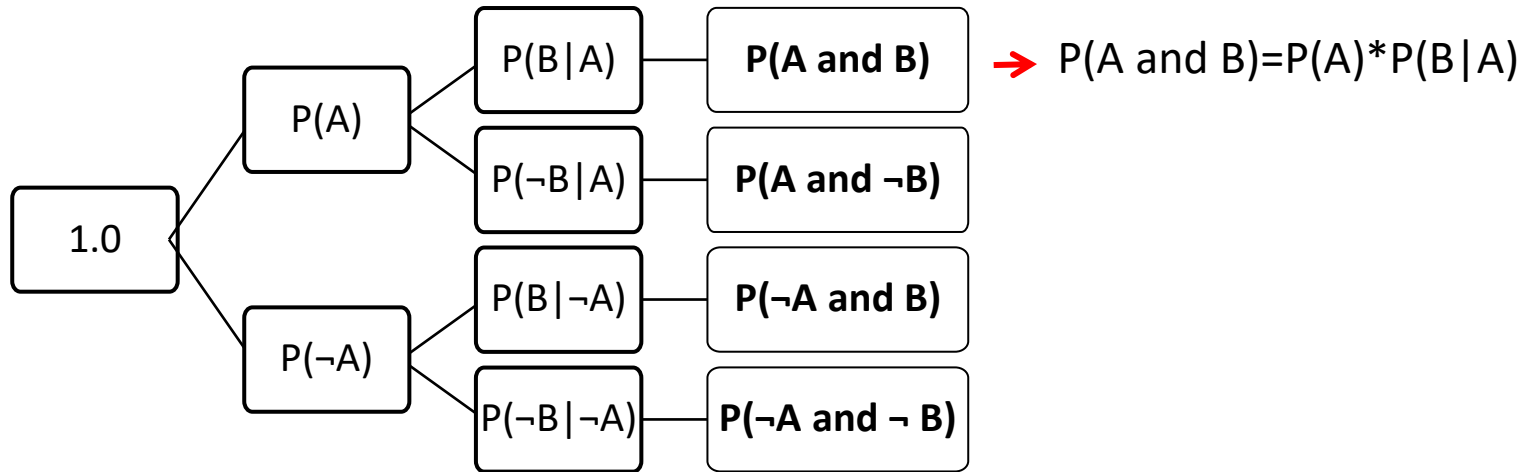


Possible event combinations when we know the outcome of event B:

$$P(B)=1/6, P(A|B)=1/4 \text{ and } P(B \text{ and } A)=1/6*1/4 = 1/24$$

But in both cases  $P(A \text{ and } B)$  is the same: orange area in the diagram

# Bayes theorem



$$P(A) * P(B|A) = P(B) * P(A|B)$$

$$P(\neg A) * P(B|\neg A) = P(B) * P(\neg A|B)$$

# Bayes theorem

Bayes theorem (formalized by Laplace)

$$P(A|E) = P(A \cap E) / P(E)$$
$$P(E|A) = P(A \cap E) / P(A)$$



Probability of  
event A given  
evidence

Probability of  
evidence given  
event A

$$P(A|E) = P(E|A)P(A)/P(E)$$

Probability of event  
A without evidence  
(*prior probability*)

**Inverse probabilities** are typically easier to ascertain



# Bayes method with probabilities

- There are 2 events: **A** and not A (**B**) which you believe occur with probabilities  $P(\mathbf{A})$  and  $P(\mathbf{B})$ . Estimation  $P(\mathbf{A}):P(\mathbf{B})$  represents odds of A vs. B.
- Collect evidence data **E**.
- Re-estimate  $P(\mathbf{A}|\mathbf{E}):P(\mathbf{B}|\mathbf{E})$  and update your beliefs.

The updated odds are computed as:

$$\frac{P(\mathbf{A}|\mathbf{E})}{P(\mathbf{B}|\mathbf{E})} = \frac{P(\mathbf{E}|\mathbf{A})P(\mathbf{A})/P(\mathbf{E})}{P(\mathbf{E}|\mathbf{B})P(\mathbf{B})/P(\mathbf{E})}$$

# Bayes' method with probabilities

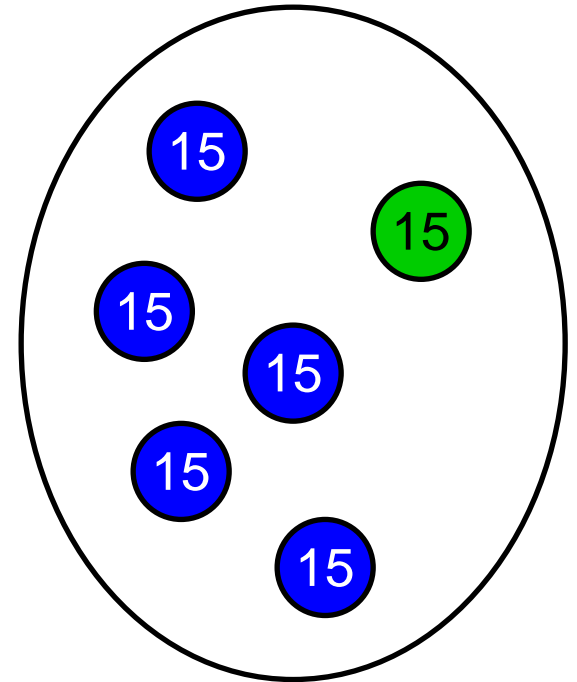
- There are 2 events: **A** and not A (**B**) which you believe occur with probabilities  $P(\mathbf{A})$  and  $P(\mathbf{B})$ . Estimation  $P(\mathbf{A}):P(\mathbf{B})$  represents odds of A vs. B.
- Collect evidence data **E**.
- Re-estimate  $P(\mathbf{A} | \mathbf{E}):P(\mathbf{B} | \mathbf{E})$  and update your beliefs.

or simply

$$\frac{P(\mathbf{A}|\mathbf{E})}{P(\mathbf{B}|\mathbf{E})} = \frac{P(\mathbf{E}|\mathbf{A})P(\mathbf{A})}{P(\mathbf{E}|\mathbf{B})P(\mathbf{B})}$$

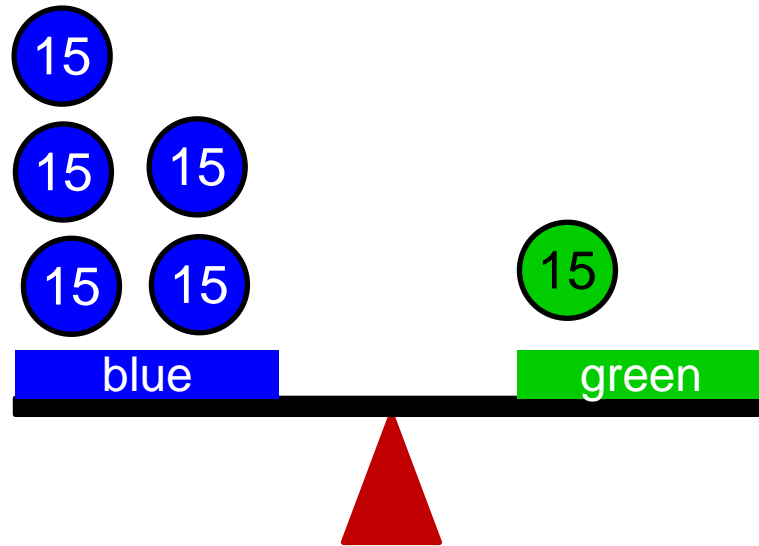
# Example: hit-and-run (fictitious)

- Taxicab company has 75 blue cabs (**B**) and 15 green cabs (**G**)
- At night when there are no other cars on the street: hit-and-run episode
- Question: what is more probable:  
**B** or **G**  
?



What is more probable:

**B** or **G**



$$P(\mathbf{B}):P(\mathbf{G})=5:1$$

# New evidence

- Witness: “I saw a green cab”:  $E_G$
  - What is the probability that the witness really saw a green car?
  - Witness is tested at night conditions: identifies correct color 4 times out of 5
- 
- The eyewitness test shows:  
 $P(E_G | G) = 4/5$  (correctly identified)  
 $P(E_G | B) = 1/5$  (incorrectly identified)

# Updating the odds

- In our case we want to compare:

the car was **G** given a witness testimony  $E_G$ :  $P(\mathbf{G} | E_G)$

vs.

the car was **B** given a witness testimony  $E_G$ :  $P(\mathbf{B} | E_G)$

Note: There is no way to know which of 2 was true, we just estimate

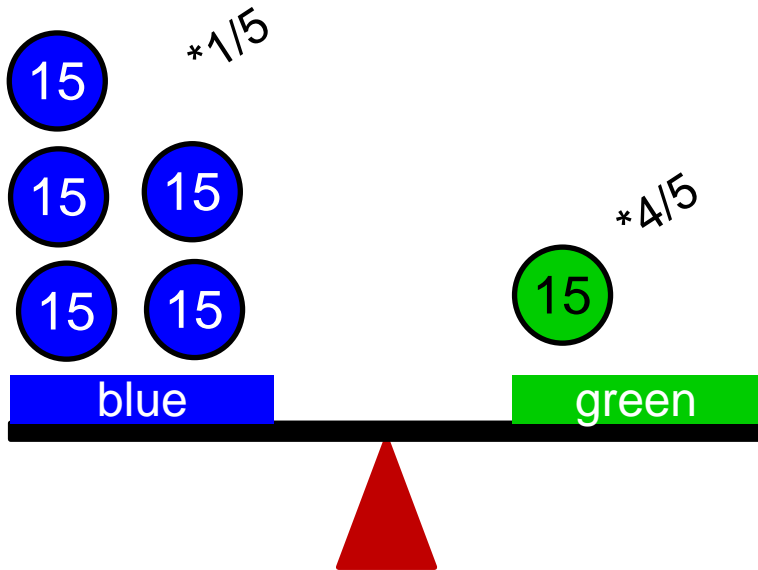
# Back to hit-and-run

All cabs were on the streets:

Prior odds ratio:  $P(\mathbf{B}) : P(\mathbf{G}) = 5/1$

Updated odds ratio:  $\frac{P(\mathbf{B} | E_G)}{P(\mathbf{G} | E_G)} = \frac{P(\mathbf{B}) * P(E_G | \mathbf{B})}{P(\mathbf{G}) * P(E_G | \mathbf{G})}$

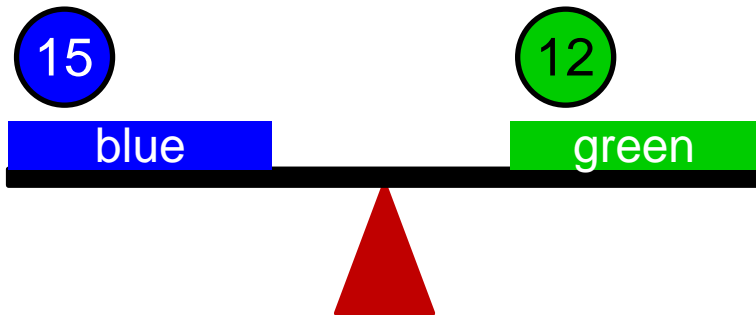
$P(E_G | \mathbf{G}) = 4/5$  (correctly identified)  
 $P(E_G | \mathbf{B}) = 1/5$  (incorrectly identified)



# New odds

$$\frac{P(\mathbf{B}|E_G)}{P(\mathbf{G}|E_G)} = \frac{P(\mathbf{B}) * P(E_G|\mathbf{B})}{P(\mathbf{G}) * P(E_G|\mathbf{G})}$$

Still 5:4 odds that the car was **B**!





# Hit-and-run: full calculation

$$P(\mathbf{B}) = 5/6, \quad P(\mathbf{G}) = 1/6$$

$$P(\mathbf{E}_G | \mathbf{G}) = 4/5 \quad P(\mathbf{E}_G | \mathbf{B}) = 1/5$$

- Probability that car was **green** given the evidence  $E_G$ :

$$P(\mathbf{G} | \mathbf{E}_G) = P(\mathbf{G}) * P(\mathbf{E}_G | \mathbf{G}) / P(\mathbf{E}_G) = [1/6 * 4/5] / P(\mathbf{E}_G) = 4/30P(\mathbf{E}_G)$$

//- 4 parts of 30P( $X_G$ )

- Probability that car was **blue** given the evidence  $X_G$ :

$$P(\mathbf{B} | \mathbf{E}_G) = P(\mathbf{B}) * P(\mathbf{E}_G | \mathbf{B}) / P(\mathbf{E}_G) = [5/6 * 1/5] / P(\mathbf{E}_G) = 5/30P(\mathbf{E}_G)$$

//- 5 parts of 30P( $X_G$ )

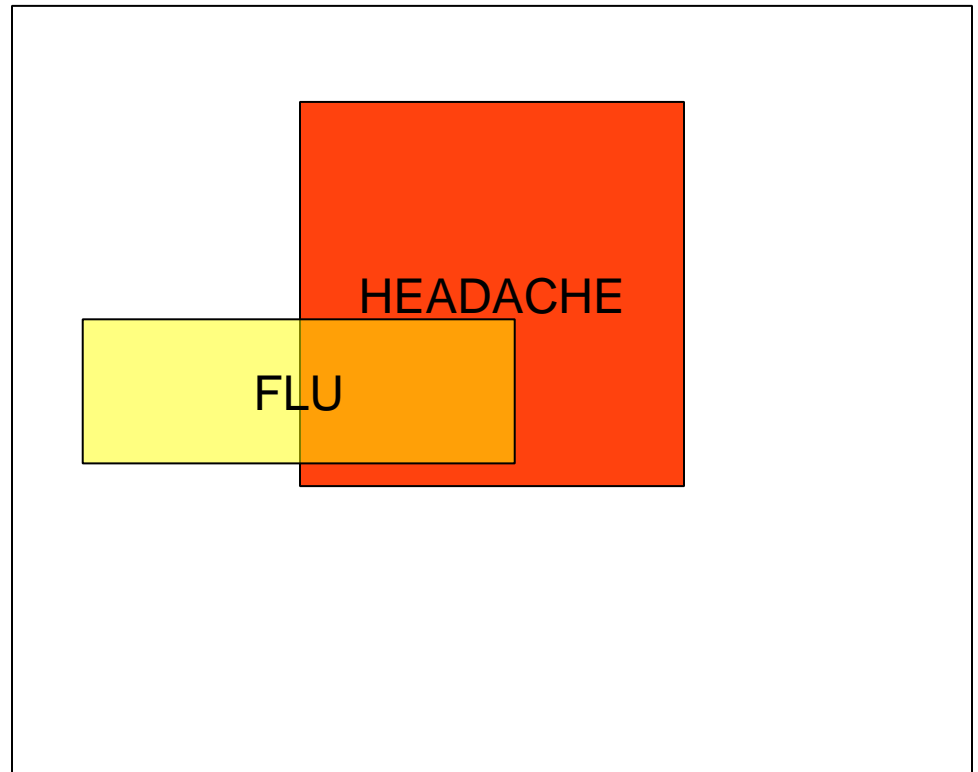
# Bayes in 'real' life. Example

$$P(H) = 1/10$$

$$P(F) = 1/40$$

$$P(H|F) = 1/2$$

$$P(F|H) = ?$$



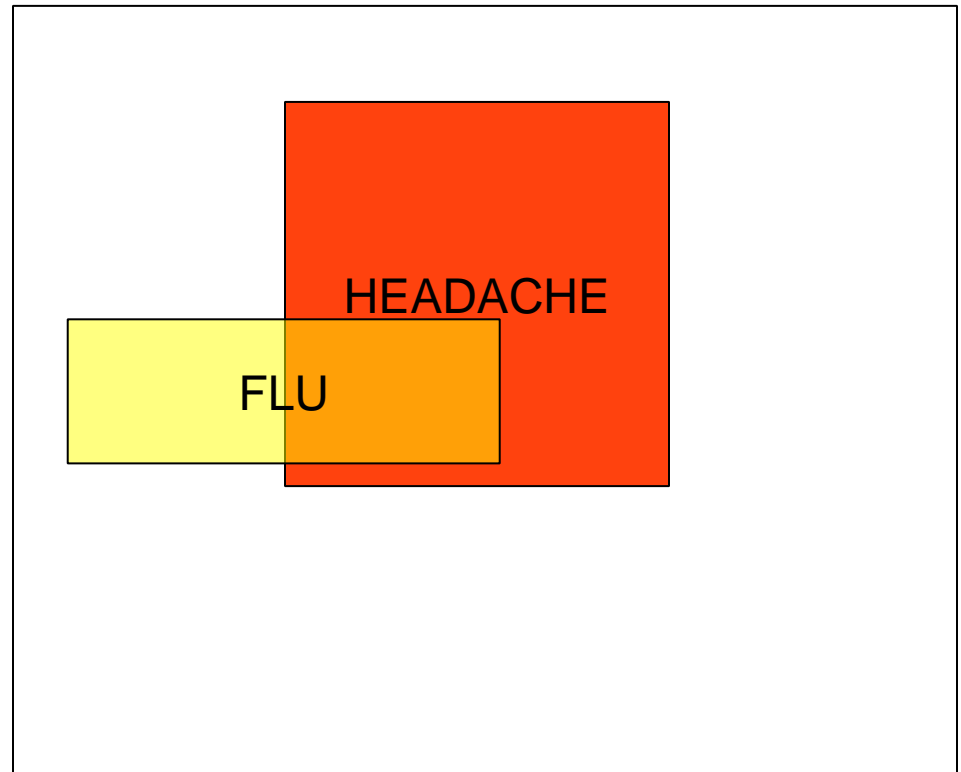
# Bayes in 'real' life. Example

$$P(H)=1/10$$

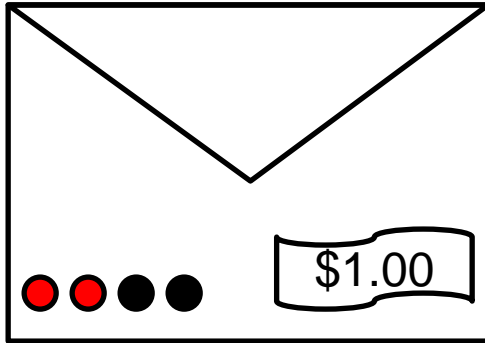
$$P(F)=1/40$$

$$P(H|F)=1/2$$

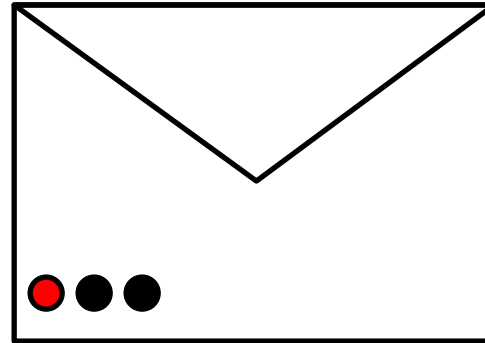
$$P(F|H) = P(H|F)P(F)/P(H)$$
$$= 1/2 * 1/40 * 10 = 1/8$$



# Bayes in 'real' life. Activity



WIN envelope

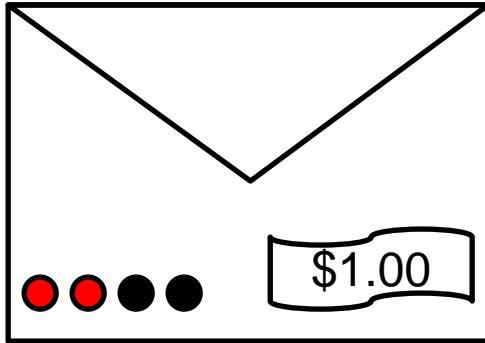


LOSE envelope

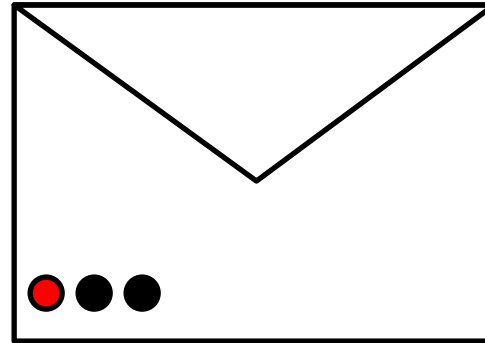
Someone draws an envelope at random and offers to sell it to you.  
How much should you pay?

The probability to win is 1:1. Pay no more than 50c.

# Bayes in 'real' life. Activity



WIN envelope



LOSE envelope

Variant: before deciding, you are allowed to see one bead drawn from the envelope.

Suppose it's black: How much should you pay?

Suppose it's red: How much should you pay?

When you want to:

- Determine the probability of having a medical condition after positive test results
- Find out a probable outcome of political elections
- Improve machine-learning performance
- Even to “prove” or “disprove” the existence of God

Use Bayesian Reasoning

# Summary: Bayes Rule for updating beliefs

$$P(A | B) = P(A) * P(B | A) / P(B)$$

$$P(\neg A | B) = P(\neg A) * P(B | \neg A) / P(B)$$

- We want to compare  $P(A | B)$  and  $P(\neg A | B)$ , i.e. given evidence B what probability is higher: that A occurred or that  $\neg A$  occurred?
- We know  $P(A)$  and  $P(\neg A)$  – prior probabilities
- We know  $P(B | A)$  and  $P(B | \neg A)$
- From Bayes' theorem:

$$P(A | B) = P(A) * P(B | A) / P(B)$$

$$P(\neg A | B) = P(\neg A) * P(B | \neg A) / P(B)$$

# Log-odds ratio

- Note, that we do not have to know  $P(b)$  in order to make predictions: we just find the ratio of 2 mutually exclusive probabilities

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

$$P(\neg A|B) = \frac{P(B|\neg A)P(\neg A)}{P(B)}$$

- Instead of finding ratio, to avoid underflow, use log:

$$\log \frac{P(A|B) = P(B|A)P(A)}{P(\neg A|B) = P(B|\neg A)P(\neg A)}$$

If positive then A is more probable, if negative then  $\neg A$  is more probable